## V10 Metabolic networks - Graph connectivity

#### Graph connectivity is related to analyzing biological networks for

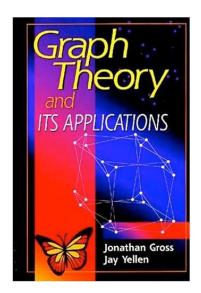
- finding cliques
- edge betweenness
- modular decomposition that have been or will be covered in forthcoming lectures.

**Cut-sets** are related to breaking up metabolic networks.

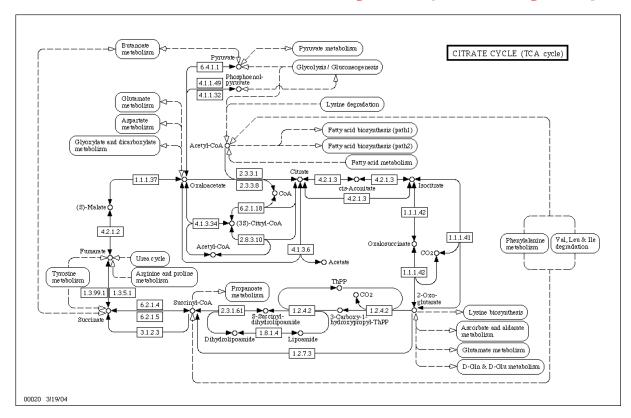
#### Today's program

V10 closely follows chapter 5.1 in the book on the right on "Vertex- and Edge-Connectivity"

V12 will cover parts of chapter 5.3 on "Max-Min Duality and Menger's Theorems"



# Citrate Cycle (TCA cycle) in E.coli

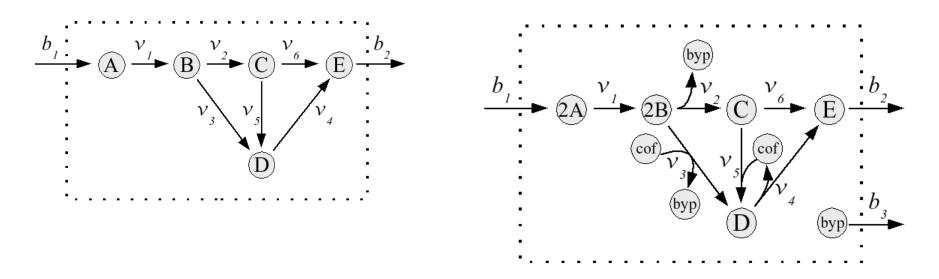


Analysis of metabolic networks is at a relatively advanced/complete stage compared to protein-interaction networks or gene-regulatory networks.

#### Possible reason:

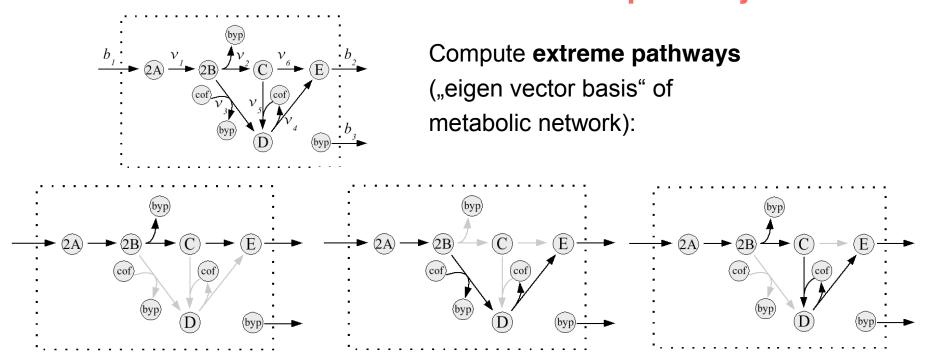
Most cellular metabolites are known.

### Motivation – simple networks – task 1



What are all the possible **steady-state flux distributions** ( $v_1$ ,  $v_2$ ,  $v_3$ ,  $v_4$ ,  $v_5$ ,  $v_6$ ) in these networks?

# Flux distributions: linear combinations of extreme pathways

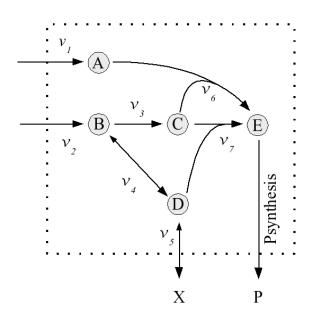


All 3 extreme pathways do not affect concentrations of internal metabolites.

These are all extreme pathways of this network.

All flux distributions in this network that can be written as linear combinations of these 3 extreme pathways are feasible steady-state flux distributions, but not others.

## Motivation – simple networks – task 2

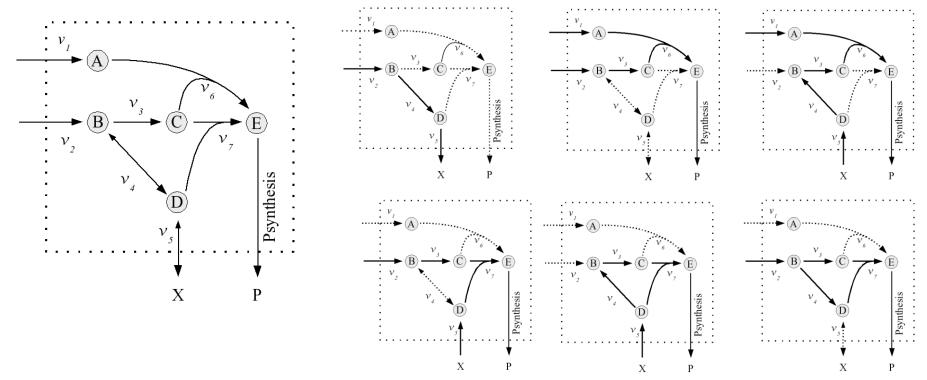


 $v_1 - v_7$  are the reaction fluxes of 7 reactions in this network that are catalyzed by transporters or enzymes 1 - 7.

P is the product of interest of this network.

What is the minimal number of reactions that need to be deleted (by gene knockouts or small molecule inhibitors) to block synthesis of P?

### **Characterize all minimal cut sets**



The system contains 6 elementary flux modes.

5 of them are coupled to synthesis of P.

Each of these must be disconnected by deleting the smallest possible number of reactions  $\rightarrow$  find all **minimal cut sets**, take the smallest one.

#### Motivation: graph connectedness

Some connected graphs are "more connected" than others.

E.g. some connected graphs can be disconnected by the removal of a single vertex or a single edge, whereas others remain connected unless more vertices or more edges are removed.

→ use vertex-connectivity and edge-connectivity to measure the connectedness of a graph.

### Motivation: graph connectedness

Determining the number of edges (or vertices) that must be removed to disconnect a given connected graph applies directly to analyzing the **vulnerability** of existing networks.

<u>Definition</u>: A graph is **connected** if for every pair of vertices u and v, there is a walk from u to v.

<u>Definition:</u> A **component** of *G* is a maximal connected subgraph of *G*.

<u>Definition</u>: A **vertex-cut** in a graph G is a vertex-set U such that G - U has more components than G.

A cut-vertex (or cutpoint) is a vertex-cut consisting of a single vertex.

<u>Definition</u>: An **edge-cut** in a graph G is a set of edges D such that G - D has more components than G.

A cut-edge (or bridge) is an edge-cut consisting of a single edge.

The **vertex-connectivity**  $\kappa_{v}(G)$  of a connected graph G is the minimum number of vertices whose removal can either disconnect G or reduce it to a 1-vertex graph.

 $\rightarrow$  if *G* has at least one pair of non-adjacent vertices, then  $\kappa_{\nu}(G)$  is the size of a smallest vertex-cut.

<u>Definition</u>: A graph G is **k-connected** if G is connected and  $\kappa_{v}(G) \ge k$ . If G has non-adjacent vertices, then G is k-connected if every vertex-cut has at least k vertices.

<u>Definition</u>: The **edge-connectivity**  $\kappa_e(G)$  of a connected graph G is the minimum number of edges whose removal can disconnect G.

 $\to$  if G is a connected graph, the edge-connectivity  $\kappa_e(G)$  is the size of a smallest edge-cut.

<u>Definition</u>: A graph G is k-edge-connected if G is connected and every edge-cut has at least k edges (i.e.  $\kappa_e(G) \ge k$ ).

Example: In the graph below, the vertex set  $\{x,y\}$  is one of three different 2-element vertex-cuts. There is no cut-vertex.  $\rightarrow \kappa_v(G) = 2$ .

The edge set  $\{a,b,c\}$  is the unique 3-element edge-cut of graph G, and there is no edge-cut with fewer than 3 edges. Therefore  $\kappa_e(G) = 3$ .

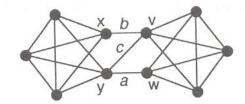


Figure 5.1.1 A graph G with  $\kappa_v(G) = 2$  and  $\kappa_e(G) = 3$ .

Application: The connectivity measures  $\kappa_v$  and  $\kappa_e$  are used in a quantified model of **network survivability**, which is the capacity of a network to retain connections among its nodes after some edges or nodes are removed.

Since neither the vertex-connectivity nor the edge-connectivity of a graph is affected by the existence or absence of self-loops, we will assume in the following that all graphs are loopless.

<u>Proposition</u> 5.1.1 Let *G* be a graph. Then the edge-connectivity  $\kappa_e(G)$  is less than or equal to the minimum degree  $\delta_{min}(G)$ .

<u>Proof</u>: Let v be a vertex of graph G with degree  $k = \delta_{min}(G)$ . Then, the deletion of the k edges that are incident on vertex separates v from the other vertices of G.  $\square$ 

<u>Definition</u>: A collection of distinct non-empty subsets  $\{S_1, S_2, ..., S_l\}$  of a set A is a **partition** of A if both of the following conditions are satisfied:

(1) 
$$S_i \cap S_j = \emptyset$$
,  $\forall 1 \le i < j \le I$ 

(2) 
$$\cup_{i=1...I} S_i = A$$

<u>Definition</u>: Let G be a graph, and let  $X_1$  and  $X_2$  form a partition of  $V_G$ .

The set of all edges of G having one endpoint in  $X_1$  and the other endpoint in  $X_2$  is called a **partition-cut** of G and is denoted  $\langle X_1, X_2 \rangle$ .

<u>Proposition</u> 4.6.3: Let  $\langle X_1, X_2 \rangle$  be a partition-cut of a connected graph G.

If the subgraphs of G induced by the vertex sets  $X_1$  and  $X_2$  are connected, then  $\langle X_1, X_2 \rangle$  is a minimal edge-cut.

<u>Proof</u>: The partition-cut  $\langle X_1, X_2 \rangle$  is an edge-cut of G, since  $X_1$  and  $X_2$  lie in different components of  $G - \langle X_1, X_2 \rangle$ .

Let S be a proper subset of  $\langle X_1, X_2 \rangle$ , and let edge  $e \in \langle X_1, X_2 \rangle$  - S. By definition of  $\langle X_1, X_2 \rangle$ , one endpoint of e is in  $X_1$  and the other endpoint is in  $X_2$ .

Thus, if the subgraphs induced by the vertex sets  $X_1$  and  $X_2$  are connected, then G - S is connected.

Therefore, S is not an edge-cut of G, which implies that  $\langle X_1, X_2 \rangle$  is a minimal edge-cut.  $\square$ 

<u>Proposition</u> 4.6.4. Let *S* be a minimal edge-cut of a connected graph *G*, and let  $X_1$  and  $X_2$  be the vertex-sets of the two components of G - S. Then  $S = \langle X_1, X_2 \rangle$ .

<u>Proof</u>: Clearly,  $S \subset \langle X_1, X_2 \rangle$ , i.e. every edge  $e \in S$  has one endpoint in  $X_1$  and one in  $X_2$ . Otherwise, the two endpoints would either both belong to  $X_1$  or to  $X_2$ . Then, S would not be minimal because S - e would also be an edge-cut of G.

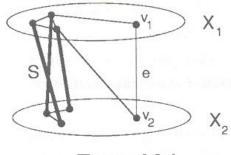
On the other hand, if  $e \in \langle X_1, X_2 \rangle$  - S, then its endpoints would lie in the same component of G - S, contradicting the definition of  $X_1$  and  $X_2$ .  $\square$ 

Remark: This assumes that the removal of a minimal edge-cut from a connected graph creates exactly two components.

<u>Proposition</u> 4.6.5. A partition-cut  $\langle X_1, X_2 \rangle$  in a connected graph G is a minimal edge-cut of G or a union of edge-disjoint minimal edge-cuts.

<u>Proof</u>: Since  $\langle X_1, X_2 \rangle$  is an edge-cut of G, it must contain a minimal edge-cut, say S.

If  $\langle X_1, X_2 \rangle \neq S$ , then let  $e \in \langle X_1, X_2 \rangle$  - S, where the endpoints  $v_1$  and  $v_2$  of e lie in  $X_1$  and  $X_2$ , respectively.



**Figure 4.6.1** 

Since S is a minimal edge-cut, the  $X_1$ -endpoints of S are in one of the components of G - S, and the  $X_2$ -endpoints are in the other component.

Furthermore,  $v_1$  and  $v_2$  are in the same component of G - S (since  $e \in G - S$ ).

Suppose, wlog, that  $v_1$  and  $v_2$  are in the same component as the  $X_1$ -endpoints of S.

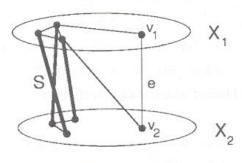


Figure 4.6.1

Then every path in G from  $v_1$  to  $v_2$  must use at least one edge of  $\langle X_1, X_2 \rangle$  - S.

Thus,  $\langle X_1, X_2 \rangle$  - S is an edge-cut of G and contains a minimal edge-cut R.

Appyling the same argument,  $\langle X_1, X_2 \rangle$  -  $(S \cup R)$  either is empty or is an edge-cut of G.

Eventually, the process ends with  $\langle X_1, X_2 \rangle$  -  $(S_1 \cup S_2 \cup ... S_r) = \emptyset$ , where the  $S_i$  are edge-disjoint minimal edge-cuts of G.  $\square$ 

<u>Proposition</u> 5.1.2. A graph *G* is *k*-edge-connected if and only if every partition-cut contains at least *k* edges.

Proof: ( $\Rightarrow$ ) Suppose, that graph G is k-edge connected. Then every partition-cut of G has at least k edges, since a partition-cut is an edge-cut.

( $\Leftarrow$ ) Suppose that every partition-cut contains at least k edges. By proposition 4.6.4., every minimal edge-cut is a partition-cut. Thus, every edge-cut contains at least k edges.  $\square$ 

<u>Proposition</u> 5.1.3. Let e be any edge of a k-connected graph G, for  $k \ge 3$ . Then the edge-deletion subgraph G - e is (k - 1)-connected.

<u>Proof</u>: Let  $W = \{w_1, w_2, ..., w_{k-2}\}$  be any set of k-2 vertices in G-e, and let x and y be any two different vertices in (G-e)-W. It suffices to show the existence of an x-y walk in (G-e)-W.

First, suppose that at least one of the endpoints of edge e is contained in set W. Since the vertex-deletion subgraph G - W is 2-connected, there is an x-y path in G - W.

This path cannot contain edge e.

Hence, it is an x-y path in the subgraph (G - e) - W.

Next suppose that neither endpoint of edge *e* is in set *W*.

Then there are two cases to consider.

Case 1: Vertices x and y are the endpoints of edge e. Graph G has at least k+1 vertices (since G is k-connected). So there exists some vertex  $z \in G - \{w_1, w_2, ..., w_{k-2}, x, y\}$ .

Since graph G is k-connected, there exists an x-z path  $P_1$  in the vertex deletion subgraph  $G - \{w_1, w_2, ..., w_{k-2}, y\}$  and a z-y path  $P_2$  in the subgraph  $G - \{w_1, w_2, ..., w_{k-2}, x\}$ 

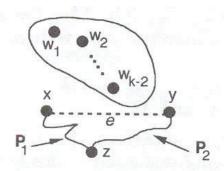


Figure 5.1.2 The existence of an x-y walk in  $(G-e)-\{w_1,w_2,\ldots,w_{k-2}\}$ .

Neither of these paths contains edge e, and, therefore, their concatenation is an x-y walk in the subgraph  $(G-e)-\{w_1,w_2,...,w_{k-2}\}$ 

Case 2: At least one of the vertices x and y, say x, is not an endpoint of edge e. Let u be an endpoint of edge e that is different from vertex x. Since graph G is k-connected, the subgraph  $G - \{w_1, w_2, ..., w_{k-2}, u\}$  is connected.

Hence, there is an x-y path P in  $G - \{w_1, w_2, ..., w_{k-2}, u\}$ .

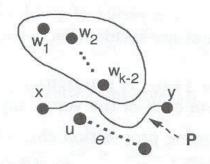


Figure 5.1.2 The existence of an x-y walk in  $(G-e)-\{w_1,w_2,\ldots,w_{k-2}\}$ .

It follows that P is an x-y path in  $G - \{w_1, w_2, ..., w_{k-2}\}$  that does not contain vertex u and, hence excludes edge e (even if P contains the other endpoint of e, which it could).

Therfore, P is an x-y path in 
$$(G-e)-\{w_1,w_2,...,w_{k-2}\}$$
.  $\square$ 

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Corollary 5.1.4. Let G be a k-connnected graph, and let D be any set of m edges of G, for  $m \le k - 1$ . Then the edge-deletion subgraph G - D is (k - m)-connected.

Proof: this follows from the iterative application of proposition 5.1.3. □

Corollary 5.1.5. Let G be a connected graph. Then  $\kappa_e(G) \ge \kappa_v(G)$ .

Proof. Let  $k = \kappa_v(G)$ , and let S be any set of k-1 edges in graph G. Since G is k-connected, the graph G-S is 1-connected, by corollary 5.1.4. Thus, the edge subset S is not an edge-cut of graph G, which implies that  $\kappa_e(G) \ge k$ .  $\square$ 

<u>Corollary</u> 5.1.6. Let *G* be a connected graph. Then  $\kappa_{v}(G) \leq \kappa_{e}(G) \leq \delta_{min}(G)$ .

This is a combination of Proposition 5.1.1 and Corollary 5.1.5. □

# Internally Disjoint Paths and Vertex-Connectivity: Whitney's Theorem

A communications network is said to be *fault-tolerant* if it has at least two alternative paths between each pair of vertices.

This notion characterizes 2-connected graphs.

A more general result for *k*-connected graphs follows later.

<u>Terminology</u>: A vertex of a path *P* is an **internal vertex** of *P* if it is neither the initial nor the final vertex of that path.

<u>Definition</u>: Let u and v be two vertices in a graph G. A collection of u-v paths in G is said to be **internally disjoint** if no two paths in the collection have an internal vertex in common.

# Internally Disjoint Paths and Vertex-Connectivity: Whitney's Theorem

<u>Theorem</u> 5.1.7 [Whitney, 1932] Let G be a connected graph with  $n \ge 3$  vertices. Then G is 2-connected if and only if for each pair of vertices in G, there are two internally disjoint paths between them.

<u>Proof</u>: ( $\Leftarrow$ ) Suppose that graph G is not 2-connected. Then let v be a cut-vertex of G. Since G - v is not connected, there must be two vertices such that there is no x-y path in G - v. It follows that v is an internal vertex of every x-y path in G.

( $\Rightarrow$ ) Suppose that graph G is 2-connected, and let x and y be any two vertices in G. We use induction on the distance d(x,y) to prove that there are at least two vertex-disjoint x-y paths in G.

If there is an edge e joining vertices x and y, (i.e., d(x,y) = 1), then the edge-deletion subgraph G - e is connected, by Corollary 5.1.4.

Thus, there is an x-y path P in G-e.

It follows that path P and edge e are two internally disjoint x-y paths in G.

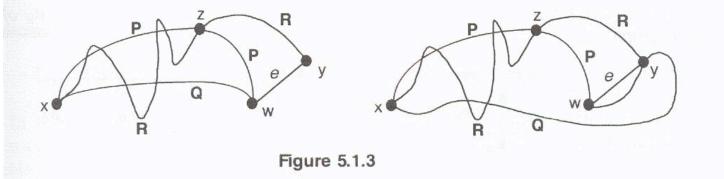
# Internally Disjoint Paths and Vertex-Connectivity: Whitney's Theorem

Next, assume for some  $k \ge 2$  that the assertion holds for every pair of vertices whose distance apart is less than k. Let x and y be vertices such that distance d(x,y) = k, and consider an x-y path of length k.

Let w be the vertex that immediately precedes vertex y on this path, and let e be the edge between vertices w and y.

Since d(x,w) < k, the induction hypothesis implies that there are two internally disjoint x-w paths in G, say P and Q.

Also, since *G* is 2-connected, there exists an *x-y* path *R* in *G* that avoids vertex *w*.



Path Q either contains vertex y (right) or it does not (left)

# Internally Disjoint Paths and Vertex-Connectivity: Whitney's Theorem

Let z be the last vertex on path R that precedes vertex y and is also on one of the paths P or Q (z might be vertex x). Assume wlog that z is on path P.

Then G has two internally disjoint x-y paths. One of these paths is the concatenation of the subgraph of P from x to z with the subpath of R from z to y.

If vertex y is not on path Q, then a second x-y path, internally disjoint from the first one, is the concatenation of path Q with the edge e joining vertex w to vertex y.

If y is on path Q, then the subpath of Q from x to y can be used as the second path.

# Internally Disjoint Paths and Vertex-Connectivity: Whitney's Theorem

Corollary 5.1.8. Let *G* be a graph with at least three vertices.

Then *G* is 2-connected if and only if any two vertices of *G* lie on a common cycle.

Proof: this follows from 5.1.7., since two vertices x and y lie on a common cycle if and only if there are two internally disjoint x-y paths.  $\square$